

A large, faint, circular seal of the University of Delaware is visible in the background on the left side. It contains the text 'UNIVERSITY OF DELAWARE' around the perimeter, '1743' at the bottom, and 'SOLVIT IN QVIETUDE' at the top. In the center, there is an open book with the words 'GRAMM', 'METAPH', 'PHILOSOPHY', 'LOGIC', 'RHETORIC', 'MATH', 'ETHICA', and 'PHYSICA' written on its pages.

FSAN/ELEG815: Statistical Learning

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6. Maximum Likelihood and Bayes Estimation

## Definition (Bayes Estimation)

**Objective:** Estimate a random parameter ( $RV$ ) from observations samples  $x_1, x_2, \dots, x_n$  that are statistically related to  $y$  by  $f_{y|\mathbf{x}}(\cdot)$

**Bayes Procedure:** Define a nonnegative cost function  $C(y, \hat{y})$  and set  $\hat{y}$  to minimize the expected cost, or risk

$$\underbrace{R}_{\text{risk}} = E\{C(y, \hat{y})\}$$

Since  $y$  and  $\hat{y}$  are  $RVs$

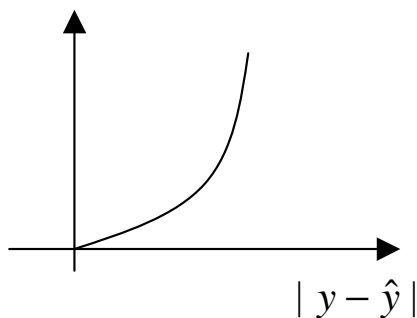
$$\begin{aligned} R &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} C(y, \hat{y}) f_{y, \mathbf{x}}(y, \mathbf{x}) dy d\mathbf{x} \\ &= \int_{-\infty}^{\infty} \underbrace{\left[ \int_{-\infty}^{\infty} C(y, \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy \right]}_{I(\hat{y})} f_{\mathbf{x}}(\mathbf{x}) d\mathbf{x} \end{aligned}$$

**Note:** Minimizing  $I(\hat{y})$  it is equivalent to minimize  $R$  since  $f_{\mathbf{x}}(\mathbf{x}) \geq 0$

Consider several cost functions

**Case 1:** Mean Squared cost function

$$C(y, \hat{y}) = |y - \hat{y}|^2$$



In this case,

$$\begin{aligned} I(\hat{y}) &= \int_{-\infty}^{\infty} (y - \hat{y})^2 f_{y|\mathbf{x}}(y|\mathbf{x}) dy \\ \Rightarrow \frac{\partial I(\hat{y})}{\partial \hat{y}} &= -2 \int_{-\infty}^{\infty} (y - \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy = 0 \end{aligned}$$

or rearranging

$$\int_{-\infty}^{\infty} \hat{y} f_{y|\mathbf{x}}(y|\mathbf{x}) dy = \int_{-\infty}^{\infty} y f_{y|\mathbf{x}}(y|\mathbf{x}) dy \quad [\hat{y} \text{ is a constant}]$$

$$\Rightarrow \hat{y}_{\text{MS}} = \int_{-\infty}^{\infty} y f_{y|\mathbf{x}}(y|\mathbf{x}) dy = E\{y|\mathbf{x}\}$$

## Example

Let  $x_i = a + \mu_i$  for  $i = 1, 2, \dots, N$ , where  $\mu_i \sim N(0, \sigma^2)$  and  $a \sim N(0, \sigma_a^2)$  are i.i.d. Determine  $\hat{a}_{\text{MS}}(\mathbf{x})$ .

Note

$$f_{\mathbf{x}|a}(\mathbf{x}|a) = \prod_{i=1}^N \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x_i-a)^2}{2\sigma^2}} = \left(\frac{1}{2\pi\sigma^2}\right)^{\frac{N}{2}} e^{-\frac{1}{2}\left(\sum_{i=1}^N \frac{(x_i-a)^2}{\sigma^2}\right)} \quad (*)$$

$$f_a(a) = \frac{1}{\sqrt{2\pi}\sigma_a} e^{-\frac{a^2}{2\sigma_a^2}} \quad (**)$$

To find  $\hat{a}_{\text{MS}}(\mathbf{x})$  we need

$$\hat{a}_{\text{MS}}(\mathbf{x}) = E\{a|\mathbf{x}\}$$

By Bayes's theorem we can write

$$f_{a|\mathbf{x}}(a|\mathbf{x}) = \frac{f_{\mathbf{x}|a}(\mathbf{x}|a)f_a(a)}{f_{\mathbf{x}}(\mathbf{x})}$$

Substituting in (\*) and (\*\*), and rearranging

$$f_{a|\mathbf{x}}(a|\mathbf{x}) = \frac{\left(\frac{1}{2\pi\sigma^2}\right)^{\frac{N}{2}} \left(\frac{1}{\sqrt{2\pi}\sigma_a}\right) e^{-\frac{1}{2}\left(\sum_{i=1}^N \frac{(x_i-a)^2}{\sigma^2} + \frac{a^2}{\sigma_a^2}\right)}}{f_{\mathbf{x}}(\mathbf{x})}$$

This can be compactly written as

$$f_{a|\mathbf{x}}(a|\mathbf{x}) = C(\mathbf{x}) \exp \left\{ -\frac{1}{2\sigma_p^2} \left[ a - \frac{\sigma_a^2}{\sigma_a^2 + \sigma^2/N} \left( \frac{1}{N} \sum_{i=1}^N x_i \right) \right]^2 \right\}$$

Observations on

$$\begin{aligned} f_{a|\mathbf{x}}(a|\mathbf{x}) &= C(\mathbf{x}) \exp \left\{ -\frac{1}{2\sigma_p^2} \left[ a - \frac{\sigma_a^2}{\sigma_a^2 + \sigma^2/N} \left( \frac{1}{N} \sum_{i=1}^N x_i \right) \right]^2 \right\} \\ &= C(\mathbf{x}) \exp \left\{ -\frac{(a - \eta)^2}{2\sigma_p^2} \right\} \end{aligned}$$

- ▶  $C(\mathbf{x})$  is a (normalizing) function of  $\mathbf{x}$  only
- ▶ The variance term is given by

$$\sigma_p^2 = \left( \frac{1}{\sigma_a^2} + \frac{N}{\sigma^2} \right)^{-1} = \frac{\sigma_a^2 \sigma^2}{N\sigma_a^2 + \sigma^2}$$

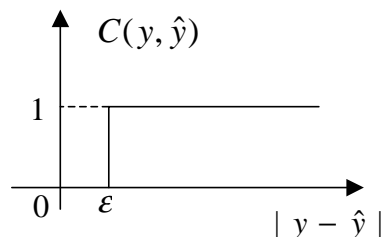
- ▶ **Critical Observation:**  $f_{a|\mathbf{x}}(a|\mathbf{x})$  is a Gaussian distribution!
- ▶ **Result:**

$$\hat{a}_{\text{MS}} = E\{a|\mathbf{x}\} = \eta = \frac{\sigma_a^2}{\sigma_a^2 + \sigma^2/N} \left( \frac{1}{N} \sum_{i=1}^N x_i \right)$$

## Case 2: Uniform cost function

$$C(y, \hat{y}) = \begin{cases} 0 & |y - \hat{y}| < \epsilon \\ 1 & \text{else} \end{cases}$$

**Question:** For what types of problems is this cost function effective?



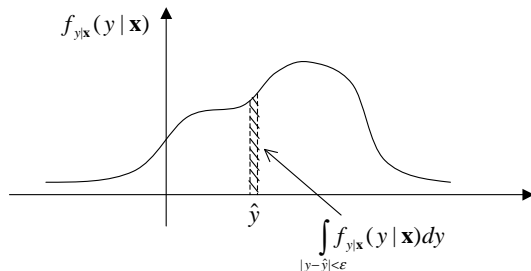
In this case,

$$\begin{aligned} I(\hat{y}) &= \int_{-\infty}^{\infty} C(y, \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy \\ &= \int_{|y-\hat{y}| \geq \epsilon} f_{y|\mathbf{x}}(y|\mathbf{x}) dy \\ &= 1 - \int_{|y-\hat{y}| < \epsilon} f_{y|\mathbf{x}}(y|\mathbf{x}) dy \end{aligned}$$

How do we minimize  $I(\hat{y})$ ?

**Result:**  $I(\hat{y})$  is minimized by  
maximizing

$$\int_{|y-\hat{y}|<\epsilon} f_{y|\mathbf{x}}(y|\mathbf{x})dy$$



**Note:**  $\epsilon$  is arbitrarily small

$\Rightarrow I(\hat{y})$  is minimized when  $f_{y|\mathbf{x}}(y|\mathbf{x})$  takes its largest value

$$\hat{y}_{\text{MAP}}(\mathbf{x}) = \underset{y}{\operatorname{argmax}} f_{y|\mathbf{x}}(y|\mathbf{x})$$

- ▶  $\hat{y}_{\text{MAP}}$  is referred to as the **maximum a posteriori** (MAP) estimate because it maximized the posterior density  $f_{y|\mathbf{x}}(y|\mathbf{x})$ .

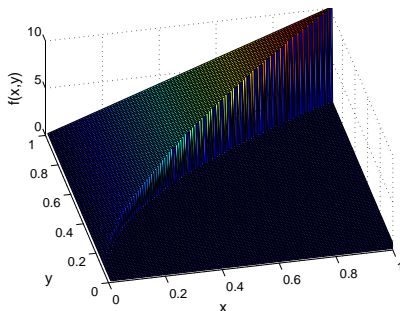
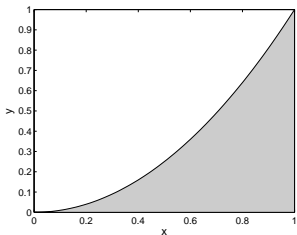


## Example

Let

$$f_{x,y}(x,y) = \begin{cases} 10y & 0 \leq y \leq x^2, 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Find the MS and MAP estimates of  $y$ , i.e.,  $\hat{y}_{\text{MS}}(x)$  and  $\hat{y}_{\text{MAP}}(x)$ .



## Example

Let

$$f_{x,y}(x,y) = \begin{cases} 10y & 0 \leq y \leq x^2, 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Find the MS and MAP estimates of  $y$ , i.e.,  $\hat{y}_{\text{MS}}(x)$  and  $\hat{y}_{\text{MAP}}(x)$ .

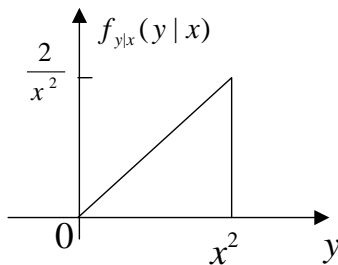
**First step:** determine the posterior density  $f_{y|x}(y|x)$ .

Since  $f_{y|x}(y|x) = \frac{f_{x,y}(x,y)}{f_x(x)}$ , we need

$$\begin{aligned} f_x(x) &= \int_{-\infty}^{\infty} f_{x,y}(x,y) dy \\ &= \int_0^{x^2} 10y dy \\ &= 5y^2 \Big|_0^{x^2} = 5x^4 \quad 0 \leq x \leq 1 \end{aligned}$$

Thus,

$$\begin{aligned} f_{y|x}(y|x) &= \frac{f_{x,y}(x,y)}{f_x(x)} \\ &= \frac{10y}{5x^4} = \frac{2y}{x^4} \quad 0 \leq y \leq x^2 \end{aligned}$$



MAP estimate:

$$\begin{aligned}\hat{y}_{\text{MAP}}(x) &= \operatorname{argmax}_y f_{y|x}(y|x) \\ &= \operatorname{argmax}_y \frac{2y}{x^4} \quad 0 \leq y \leq x^2 \\ &= x^2\end{aligned}$$

MS estimate:

$$\begin{aligned}\hat{y}_{\text{MS}}(x) &= E\{y|x\} \\ &= \int_0^{x^2} y f_{y|x}(y|x) dy \\ &= \int_0^{x^2} \frac{2y^2}{x^4} dy \\ &= \left. \frac{2}{3} \frac{y^3}{x^4} \right|_0^{x^2} = \frac{2}{3} x^2\end{aligned}$$

Note that the minimum MSE is

$$\begin{aligned} E\{(y - \hat{y}_{\text{MS}})^2\} &= \int_0^1 \int_0^{x^2} (y - \hat{y}_{\text{MS}})^2 f_{x,y}(x,y) dy dx \\ &= \int_0^1 \int_0^{x^2} (y - \frac{2}{3}x^2)^2 10y dy dx = \frac{5}{162} = 0.0309 \end{aligned}$$

The MSE of the MAP estimate is

$$\begin{aligned} E\{(y - \hat{y}_{\text{MAP}})^2\} &= \int_0^1 \int_0^{x^2} (y - \hat{y}_{\text{MAP}})^2 f_{x,y}(x,y) dy dx \\ &= \int_0^1 \int_0^{x^2} (y - x^2)^2 10y dy dx = \frac{5}{54} = 0.0926 \end{aligned}$$

**Observation:** This result is expected. Why?

**Observation:** MAP estimation can be used as an extension of ML estimation if some variability is assumed

- ▶ Instead of an unknown constant  $\theta$ , we have an unknown random parameter with distribution  $f_{\theta}(\theta)$

To see this, note

$$f_{\theta|\mathbf{x}}(\theta|\mathbf{x}) = \frac{f_{\mathbf{x}|\theta}(\mathbf{x}|\theta)f_{\theta}(\theta)}{f_{\mathbf{x}}(\mathbf{x})}$$

- ▶ The MAP estimate maximizes the numerator since  $f_{\mathbf{x}}(\mathbf{x})$  is not a function of  $\theta$ ,

$$\hat{\theta}_{\text{MAP}} = \underset{\theta}{\operatorname{argmax}} f_{\mathbf{x}|\theta}(\mathbf{x}|\theta)f_{\theta}(\theta)$$

**Question:** For what distribution  $f_{\theta}(\theta)$  does  $\hat{\theta}_{\text{MAP}} = \hat{\theta}_{\text{ML}}$ ?

That is

$$\hat{\theta}_{\text{MAP}} = \underset{\theta}{\operatorname{argmax}} f_{\mathbf{x}|\theta}(\mathbf{x}|\theta)f_{\theta}(\theta) \stackrel{?}{=} \underset{\theta}{\operatorname{argmax}} f_{\mathbf{x}|\theta}(\mathbf{x}|\theta) = \hat{\theta}_{\text{ML}}$$

## Example

Let  $x(n) = A + \mu(n)$  for  $n = 1, 2, \dots, N$ , where  $\mu(n) \sim N(0, \sigma_\mu^2)$  and  $A \sim N(A_0, \sigma_A^2)$  are i.i.d.

Determine the MAP estimate of  $A$ .

Need to maximize  $f_{\mathbf{x}|A}(\mathbf{x}|A)f_A(A)$ , or

$$\hat{A}_{\text{MAP}} = \operatorname{argmax}_A \left[ \ln(f_{\mathbf{x}|A}(\mathbf{x}|A)) + \ln(f_A(A)) \right]$$

Note

$$\ln(f_{\mathbf{x}|A}(\mathbf{x}|A)) = \frac{N}{2} \ln \left( \frac{1}{2\pi\sigma_\mu^2} \right) - \sum_{n=0}^N \frac{(x(n) - A)^2}{2\sigma_\mu^2}$$

and

$$\ln(f_A(A)) = \frac{1}{2} \ln \left( \frac{1}{2\pi\sigma_A^2} \right) - \frac{(A - A_0)^2}{2\sigma_A^2}$$

Thus

$$\hat{A}_{\text{MAP}} = \underset{A}{\operatorname{argmin}} \left( \frac{1}{2\sigma_{\mu}^2} \sum_{n=1}^N (x(n) - A)^2 + \frac{(A - A_0)^2}{2\sigma_A^2} \right)$$

Differentiating we get

$$-\frac{1}{\sigma_{\mu}^2} \sum_{n=1}^N (x(n) - A) + \frac{(A - A_0)}{\sigma_A^2} \Big|_{A=\hat{A}_{\text{MAP}}} = 0$$

$$\Rightarrow \sum_{n=1}^N \frac{x(n)}{\sigma_{\mu}^2} - \frac{N\hat{A}_{\text{MAP}}}{\sigma_{\mu}^2} = \frac{\hat{A}_{\text{MAP}}}{\sigma_A^2} - \frac{A_0}{\sigma_A^2}$$

$$\Rightarrow \hat{A}_{\text{MAP}} \left( \frac{1}{\sigma_A^2} + \frac{N}{\sigma_{\mu}^2} \right) = \frac{1}{\sigma_{\mu}^2} \sum_{n=1}^N x(n) + \frac{A_0}{\sigma_A^2}$$

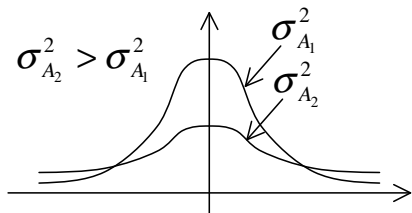
$$\Rightarrow \hat{A}_{\text{MAP}} = \frac{1}{\frac{1}{\sigma_A^2} + \frac{N}{\sigma_{\mu}^2}} \left( \frac{1}{\sigma_{\mu}^2} \sum_{n=1}^N x(n) + \frac{A_0}{\sigma_A^2} \right)$$



$$\hat{A}_{\text{MAP}} = \frac{1}{\frac{1}{\sigma_A^2} + \frac{N}{\sigma_\mu^2}} \left( \frac{1}{\sigma_\mu^2} \sum_{n=1}^N x(n) + \frac{A_0}{\sigma_A^2} \right)$$

Note that if  $\sigma_A^2 \rightarrow \infty$  then there is no *a priori* information and

$$\lim_{\sigma_A^2 \rightarrow \infty} \hat{A}_{\text{MAP}} = \frac{1}{N} \sum_{n=1}^N x(n) = \hat{A}_{\text{ML}}$$



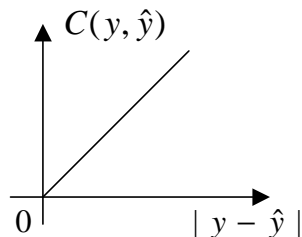
**Observation:** As  $f_\theta(\theta)$  flattens out

$$\hat{\theta}_{\text{MAP}} \rightarrow \hat{\theta}_{\text{ML}}$$

## Case 3: The absolute cost function

$$C(y, \hat{y}) = |y - \hat{y}|$$

**Question:** For what types of problems is this cost function effective?



In this case

$$\begin{aligned} I(\hat{y}) &= \int_{-\infty}^{\infty} C(y, \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy \\ &= \int_{y < \hat{y}} (\hat{y} - y) f_{y|\mathbf{x}}(y|\mathbf{x}) dy + \int_{y \geq \hat{y}} (y - \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy \\ &= \int_{-\infty}^{\hat{y}} (\hat{y} - y) f_{y|\mathbf{x}}(y|\mathbf{x}) dy + \int_{\hat{y}}^{\infty} (y - \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy \end{aligned}$$

$$I(\hat{y}) = \int_{-\infty}^{\hat{y}} (\hat{y} - y) f_{y|\mathbf{x}}(y|\mathbf{x}) dy + \int_{\hat{y}}^{\infty} (y - \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy$$

Note that

$$\int_{-\infty}^{\hat{y}} (\hat{y} - y) f_{y|\mathbf{x}}(y|\mathbf{x}) dy = \hat{y} F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) - \int_{-\infty}^{\hat{y}} y f_{y|\mathbf{x}}(y|\mathbf{x}) dy$$

and similarly

$$\int_{\hat{y}}^{\infty} (y - \hat{y}) f_{y|\mathbf{x}}(y|\mathbf{x}) dy = \int_{\hat{y}}^{\infty} y f_{y|\mathbf{x}}(y|\mathbf{x}) dy - \hat{y}(1 - F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}))$$

Thus,

$$\begin{aligned} I(\hat{y}) &= \hat{y} F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) - \int_{-\infty}^{\hat{y}} y f_{y|\mathbf{x}}(y|\mathbf{x}) dy \\ &\quad - \hat{y}(1 - F_{y|\mathbf{x}}(\hat{y}|\mathbf{x})) + \int_{\hat{y}}^{\infty} y f_{y|\mathbf{x}}(y|\mathbf{x}) dy \end{aligned}$$

$$\begin{aligned}
 I(\hat{y}) &= \hat{y}F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) - \int_{-\infty}^{\hat{y}} yf_{y|\mathbf{x}}(y|\mathbf{x})dy \\
 &\quad - \hat{y}(1 - F_{y|\mathbf{x}}(\hat{y}|\mathbf{x})) + \int_{\hat{y}}^{\infty} yf_{y|\mathbf{x}}(y|\mathbf{x})dy
 \end{aligned}$$

Taking the derivative

$$\begin{aligned}
 \frac{\partial I(\hat{y})}{\partial \hat{y}} &= F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) + \hat{y}f_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) - \hat{y}f_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) \\
 &\quad - (1 - F_{y|\mathbf{x}}(\hat{y}|\mathbf{x})) + \hat{y}f_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) - \hat{y}f_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) \\
 &= F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}) - (1 - F_{y|\mathbf{x}}(\hat{y}|\mathbf{x}))
 \end{aligned}$$

**Result:** Setting equal to 0, we see the  $\hat{y}_{\text{MAE}}$  is given by

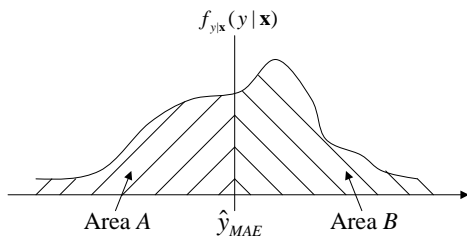
$$F_{y|\mathbf{x}}(\hat{y}_{\text{MAE}}|\mathbf{x}) = 1 - F_{y|\mathbf{x}}(\hat{y}_{\text{MAE}}|\mathbf{x})$$

or

$$\int_{-\infty}^{\hat{y}_{\text{MAE}}} f_{y|\mathbf{x}}(y|\mathbf{x})dy = \int_{\hat{y}_{\text{MAE}}}^{\infty} f_{y|\mathbf{x}}(y|\mathbf{x})dy$$

$$\int_{-\infty}^{\hat{y}_{MAE}} f_{y|\mathbf{x}}(y|\mathbf{x}) dy = \int_{\hat{y}_{MAE}}^{\infty} f_{y|\mathbf{x}}(y|\mathbf{x}) dy$$

Interpreting this graphically



$$\text{Area } A = \text{Area } B$$

Observation:

$$\hat{y}_{MAE} = \text{median of } f_{y|\mathbf{x}}(y|\mathbf{x})$$

# Estimator Relations

- ▶ If  $f_{y|\mathbf{x}}(y|\mathbf{x})$  is symmetric, then

$$\hat{y}_{\text{MAE}} = \hat{y}_{\text{MS}}$$

Why?

For a symmetric distribution the conditional mean is equal to the (median) symmetry point

- ▶ If  $f_{y|\mathbf{x}}(y|\mathbf{x})$  is symmetric and unimodal, then

$$\hat{y}_{\text{MAE}} = \hat{y}_{\text{MS}} = \hat{y}_{\text{MAP}}$$

Why? The unimodal constraint implies that the single mode must be at the distribution symmetry point  $\Rightarrow$  the MAP estimate is located at the central point

## Example

Determine  $\hat{y}_{\text{MAE}}$  for the previously considered case

$$f_{x,y}(x,y) = \begin{cases} 10y & 0 \leq y \leq x^2, 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

We showed previously that

$$f_{y|x}(y|x) = \frac{2y}{x^4} \quad 0 \leq y \leq x^2 \quad \Rightarrow \quad F_{y|x}(y|x) = \frac{y^2}{x^4} \quad 0 \leq y \leq x^2$$

Thus determining  $\hat{y}_{\text{MAE}}$

$$\begin{aligned} F_{y|x}(\hat{y}_{\text{MAE}}|x) &= 1 - F_{y|x}(\hat{y}_{\text{MAE}}|x) \\ \Rightarrow \frac{\hat{y}_{\text{MAE}}^2}{x^4} &= 1 - \frac{\hat{y}_{\text{MAE}}^2}{x^4} \\ \Rightarrow \hat{y}_{\text{MAE}} &= \frac{x^2}{\sqrt{2}} \end{aligned}$$

MAP estimate: (previous result)

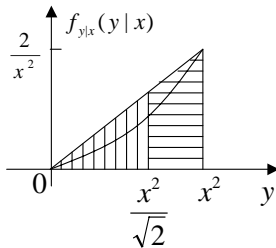
$$\hat{y}_{\text{MAP}}(x) = \operatorname{argmax}_y f_{y|x}(y|x) = x^2$$

MS estimate: (previous result)

$$\hat{y}_{\text{MS}}(x) = E\{y|x\} = \frac{2}{3}x^2$$

MAE estimate:

$$\hat{y}_{\text{MAE}}(x) = \text{median of } f_{y|x}(y|\mathbf{x}) = \frac{x^2}{\sqrt{2}}$$





# Final ML and MAP Comments

- ▶ ML estimation was pioneered by geneticist and statistician Sir R. A. Fisher between 1912 and 1922
- ▶ Under fairly weak regularity conditions the ML estimate is **asymptotically optimal**
  - ▶ The ML estimate is asymptotically unbiased, i.e., its bias tends to zero as the number of samples increases to infinity
  - ▶ The ML estimate is asymptotically efficient, i.e., it achieves the Cramér-Rao lower bound when the number of samples tends to infinity
  - Consequence:** No unbiased estimator has lower mean squared error than the ML estimator
  - ▶ The ML estimate is asymptotically normal, i.e., as the number of samples increases, the distribution of the ML estimate tends to the Gaussian distribution
- ▶ MAP estimation is a generalization of ML estimation that incorporates the **prior distribution** of the quantity being estimated